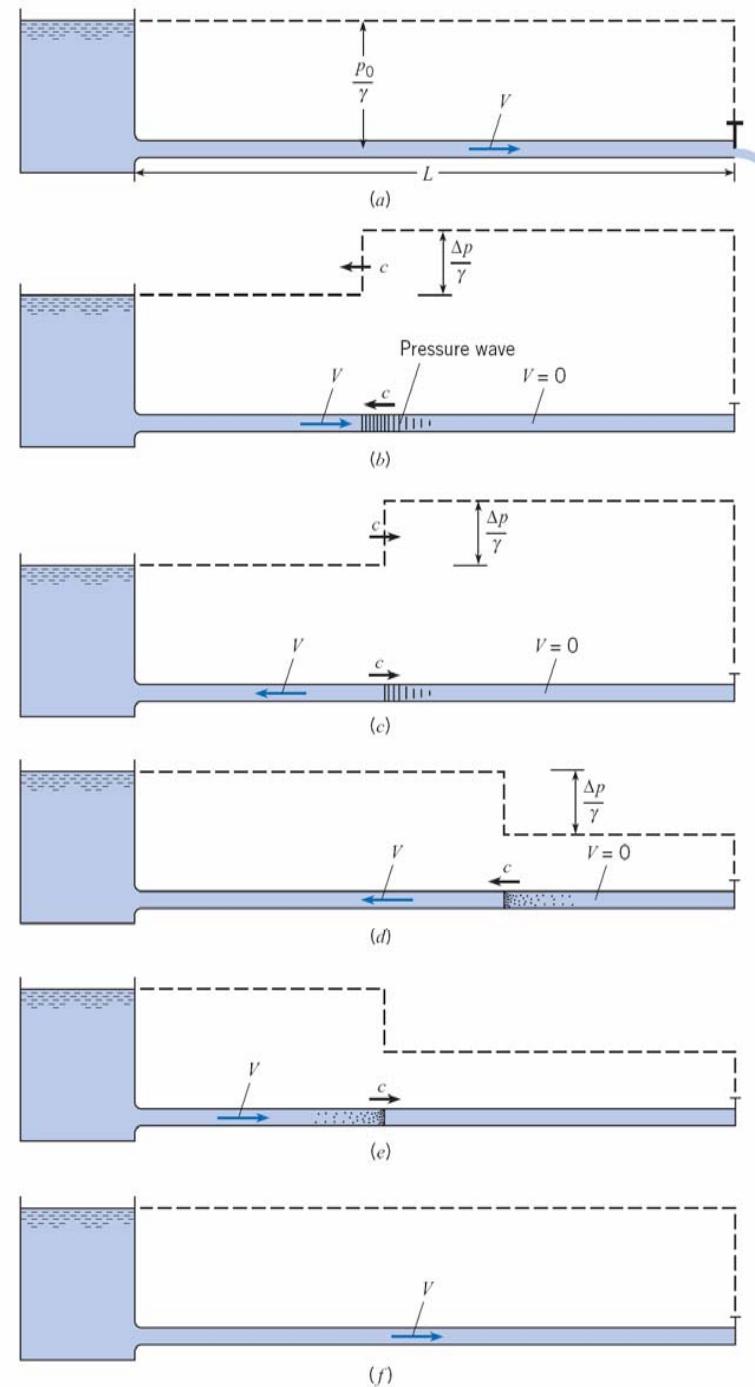
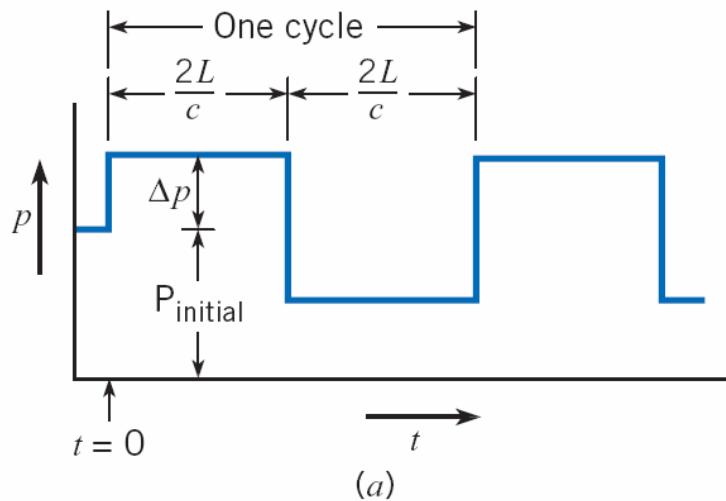


# Water Hammer

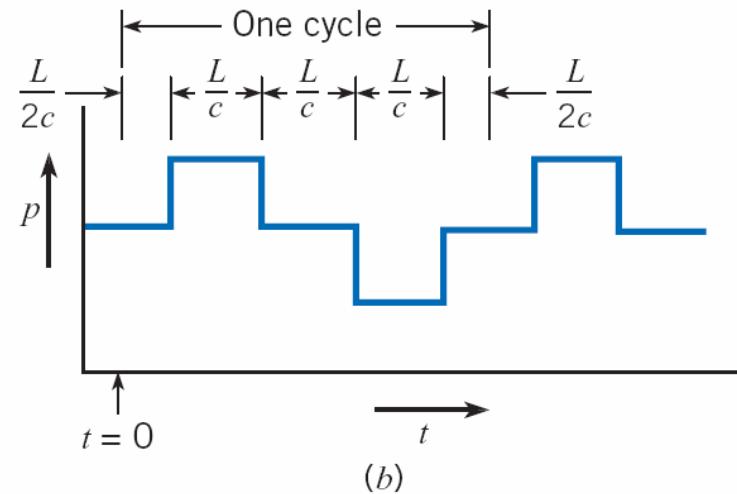
## Water hammer process.

- (a) Initial condition.
- (b) Condition during time  $0 < t < L/c$ .
- (c) Condition during time  $L/c < t < 2L/c$ .
- (d) Condition during time  $2L/c < t < 3L/c$ .
- (e) Condition during time  $2L/c < t < 4L/c$ .
- (f) Condition at time  $t = 4L/c$ .

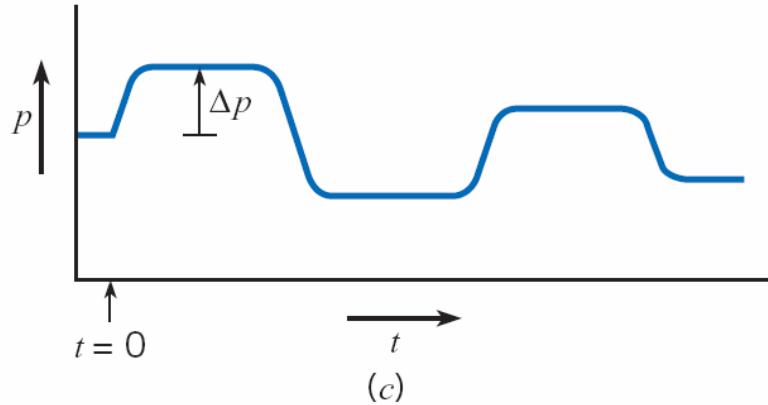




(a)



(b)

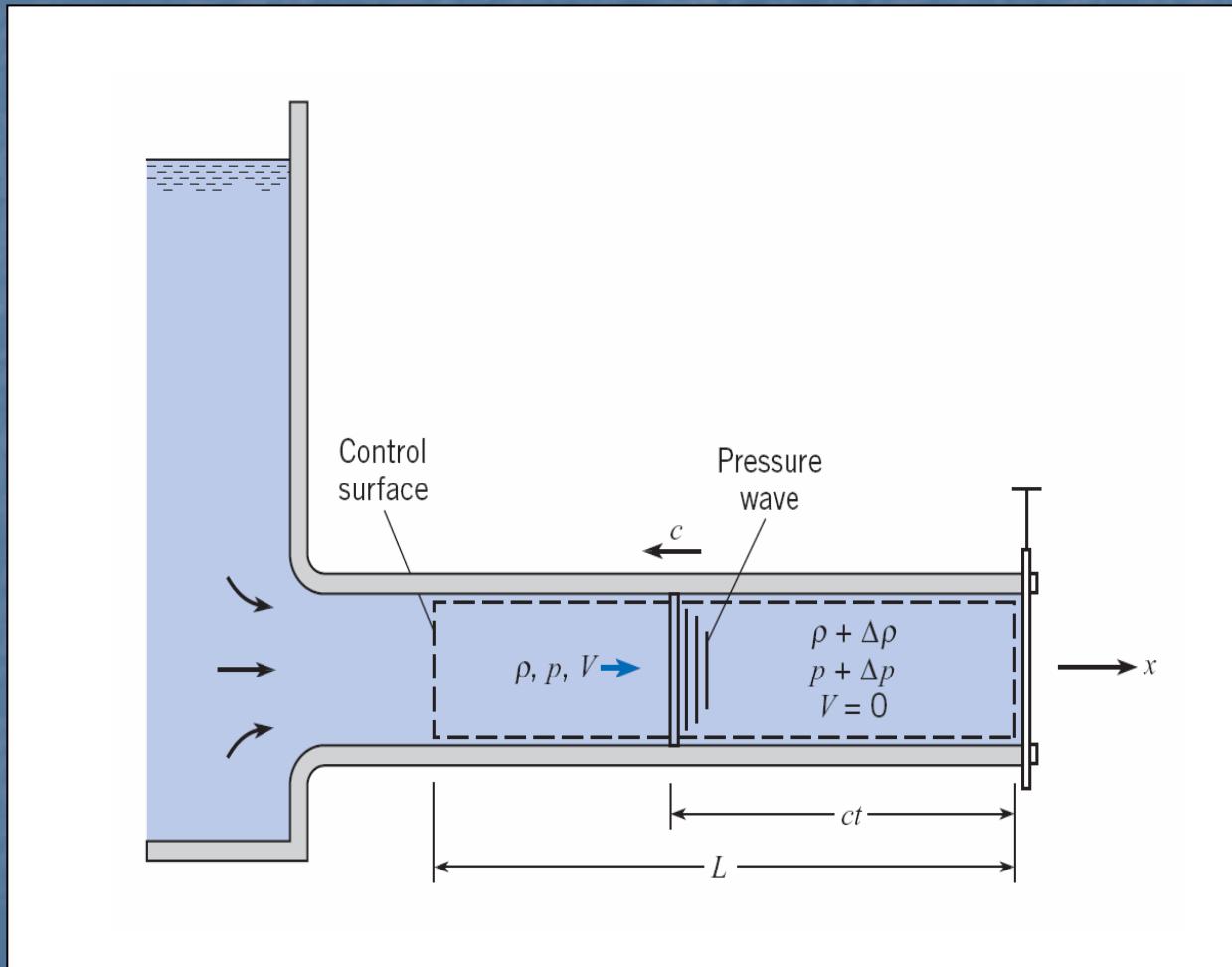


(c)

## Variation of water-hammer pressure with time at two points in a pipe.

- (a) Location: adjacent to valve.
- (b) Location: at midpoint of pipe.
- (c) Actual variation of pressure near valve.

# Magnitude of Water Hammer Pressure and Speed of Pressure Wave



$$-\Delta p A = -\rho v c A - \rho A v^2$$

$$\Delta p = \rho v c + \rho v^2$$

The term  $(\rho v^2)$  can be neglected with respect to the first term because  $(c)$  for liquid is much greater than  $(v)$ . therefore, the above Eqn. becomes

$$\Delta p = \rho v c$$

Applying the continuity principle to the control volume

$$0 = \frac{d}{dt} \int_{cv} \rho dQ + \sum_{cs} (\dot{m})_{outX} - \sum_{cs} (\dot{m})_{inX}$$

$$0 = -\dot{m}_{in} + \frac{d}{dt} [\rho(L - ct)A + (\rho + \Delta\rho)ctA]$$

$$0 = -\rho v A + [-(\rho c A) + (\rho c A + \Delta\rho c A)]$$

$$\frac{\Delta\rho}{\rho} = \frac{v}{c}$$

Hence  $c = \frac{v}{\Delta\rho/\rho}$

By definition, the gas compressibility

$$E_v = \frac{\Delta p}{\Delta\rho/\rho} = \rho$$

$$c = \frac{vE_v}{\Delta p} = \frac{vE_v}{\rho vc}$$

$$c = \sqrt{\frac{E_v}{\rho}}$$

# Moment - of - Momentum Equation

For rotational motion, the angular momentum of a system is given by,

$$\sum M = \frac{d(H)_{sys}}{dt}$$

*M = The moment*

*H<sub>sys</sub> = angular momentum of the system*

Using the Reynolds transport theorem which is

$$\frac{dB_{sys}}{dt} = \frac{d}{dt} \int_{cv} b \rho dQ + \int_{cs} b \rho V \bullet dA$$

$$B_{sys} = (H)_{sys} = (mvr)_{sys} \quad b = vr$$

$$\frac{d(H)_{sys}}{dt} = \frac{d}{dt} \int_{cv} (v \times r) \rho dQ + \int_{cs} (v \times r) \rho V \bullet dA = \sum M$$

$$\sum M = \frac{d}{dt} \int_{cv} (r \times v) \rho dQ + \sum_{cs} r \times (\dot{m}v)_{out} - \sum_{cs} r \times (\dot{m}v)_{in}$$

# MOMENTUM PRINCIPLE

## The Momentum Equation for Cartesian Coordinates

X-direction:

$$\sum F_x = \frac{d}{dt} \int_{cv} v_x \rho dQ + \sum_{CS} (\dot{mv})_{outX} - \sum_{CS} (\dot{mv})_{inX}$$

Y-direction:

$$\sum F_y = \frac{d}{dt} \int_{cv} v_y \rho dQ + \sum_{CS} (\dot{mv})_{outY} - \sum_{CS} (\dot{mv})_{inY}$$

Z-direction:

$$\sum F_z = \frac{d}{dt} \int_{cv} v_z \rho dQ + \sum_{CS} (\dot{mv})_{outZ} - \sum_{CS} (\dot{mv})_{inZ}$$

## Moment - of - Momentum Equation

$$\sum M = \frac{d}{dt} \int_{CV} (r \times v) \rho dQ + \sum_{CS} r \times (\dot{mv})_{out} - \sum_{CS} r \times (\dot{mv})_{in}$$

# END OF LECTURE (6)